8186786411

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Amended Claim Listing

- 1. (Previously Presented) An apparatus for free motion stitching and for inserting stitches of uniform length through a stack of one or more fabric layers as said stack is manually guided in a substantially horizontal plane, said apparatus comprising:
- a fixedly located stitch head including a needle mounted for cyclic vertical movement:
- a bed defining a substantially horizontally oriented first planar surface mounted opposite to said stitch head;
- a frame configured to retain said fabric layer stack in a substantially taut condition adjacent to said first planar surface;
- at least one bearing supporting said frame for manually guided movement to move said stack across said first planar surface;
- a detector for producing one or more signals representing the magnitude of translational movement of said frame; and
- control circuitry responsive to said detector signals indicating a magnitude of translational movement exceeding a threshold magnitude for causing said needle to execute a cyclic movement from an up position remote from said stack, to a down position piercing said stack, and back to said up position.

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(Cancelled)

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3. (Currently Amended) The apparatus of claim 1 wherein said bearings emprise wheels at least one bearing comprises a wheel.

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4. (Currently Amended) The apparatus of claim 1 wherein said bearings comprise slide members at least one bearing comprises a slide member.

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5. (Previously Presented) The apparatus of claim 1 wherein said detector is coupled to said frame for movement therewith.

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| 1. | 6. | (Original) | The apparat | us of clai | m 5 where | ein said de | etector com | iprises an |
|----|--|----------------|-----------------|------------|-------------|--------------|---------------|-------------|
| 2 | optical detector responsive to light reflected from said second planar surface. | | | | | | | |
| 3 | | | | | | | | |
| 4 | 7. | (Previously F | Presented) | The app | paratus of | claim 1 w | herein said | detector |
| 5 | comprises at least one arm linked to said frame for movement therewith and means | | | | | | | |
| 6 | responsive to movement of said arm for producing said signals. | | | | | | | |
| 7 | | | | | | | | |
| 8 | 8. | (Previously F | Presented) | A meth | od of for | ming suc | cessive st | titches of |
| 9 | uniform length while free motion stitching through a stack of fabric layers, said method | | | | | | | |
| 10 | comprising: | • | | | | | | |
| 11 | | mounting ar | actuatable : | stitch hea | ad at a fi | xed locat | ion above | a planar |
| 12 | surface; | | | | | | | |
| 13 | | mounting a s | stack of fabric | layers to | a frame; | | | |
| 14 | manually moving said frame to guide said stack across said planar surface; | | | | | | | r surface; |
| 15 | | detecting the | movement o | f said fra | me; and | • | | |
| 16 | · | actuating sai | id stitch head | in respor | ise to a m | nagnitude | of frame m | novement |
| 17 | greater than | a threshold m | agnitude to ca | use a ne | edle in sa | id stitch he | ead to mov | e from an |
| 18 | up position remote from said stack, to a down position piercing said stack, and back to | | | | | | | |
| 19 | said up position | | | | | | | |
| 20 | | | | | | | | |
| 21 | 9. | (Original) | The method | of claim 8 | wherein s | stitch head | l is actuated | d at a rate |
| 22 | proportional | to the rate of | translational r | novemen | t of said f | rame. | | |
| 23 | <i>II</i> | | | | | | | |
| 24 | // | | | | | | | |
| 25 | # . | | | | | | | |
| 26 | <i>!</i> / | | | | | | | |
| 7 | <i>//</i> | | | | | | | |
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10.

(Previously Presented)

A method of forming successive stitches of

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| 2 | uniform length while free motion stitching through a stack of fabric layers, said method | | | | | |
|------------|---|--|--|--|--|--|
| 3 . | comprising: | | | | | |
| 4 | mounting an actuatable stitch head at a fixed location above a plana | | | | | |
| 5 | surface; | | | | | |
| 6 | mounting a stack of fabric layers to a frame; | | | | | |
| 7 | manually moving said frame to guide said stack across said planar surface | | | | | |
| 8 | detecting the movement of said frame; and | | | | | |
| 9 | controlling said stitch head to cause a needle to execute cyclic movements | | | | | |
| 10 | at a rate proportional to the speed of movement of said frame. | | | | | |
| 11 | | | | | | |
| 12 | 11. (Previously Presented) An apparatus for free motion stitching and for | | | | | |
| 13 | inserting stitches of uniform length through a stack of one or more fabric layers as said | | | | | |
| 14 | stack is manually guided in a substantially horizontal plane, said apparatus comprising: | | | | | |
| 15 | a fixedly located stitch head including a пeedle mounted for cyclic vertical | | | | | |
| 16 | movement; | | | | | |
| 17 | a bed defining a substantially horizontally oriented first planar surface | | | | | |
| 18 | mounted opposite to said stitch head; | | | | | |
| 19 | a frame configured to retain said fabric layer stack in a substantially taut | | | | | |
| 20 | condition adjacent to said first planar surface, | | | | | |
| 21 | at least one bearing supporting said frame for manually guided movement | | | | | |
| 22 | across a substantially horizontally oriented second planar surface to move said stack | | | | | |
| 23 | across said first planar surface; | | | | | |
| 24 | a detector for measuring the movement of said frame across said second | | | | | |
| 25 | planar surface; and | | | | | |
| 26 | control circuitry for causing said needle to execute cyclic movements at a | | | | | |
| 27 | rate substantially proportional to the rate of frame movement measured by said detector. | | | | | |
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12. (Original) Apparatus for use in combination with a sewing machine which 1 2 includes a drive subsystem configured to cycle a needle through a path of vertical 3 movement from an up position to a down position and back to said up position, said apparatus comprising: 4 a frame; 5 means for removably securing a stack of one or more fabric layers to said 6 frame: 7 8 bearing means mounting said frame for hand guided movement across a planar surface; 9 10 detector means for producing signals representing the magnitude of translational movement of said frame across said planar surface; and 11 12 means for coupling said signals to said drive subsystem to synchronize the cycle rate of said needle to the translational movement of said frame. 13 14 13. (Original) The apparatus of claim 12 wherein said bearing means 15 16 comprises at least one wheel. 17 (Original) The apparatus of claim 12 wherein said detector means 18 produces signals representing the magnitude of frame translation along first and second 19 perpendicular directions. 20 21 15. 22 (Original) The apparatus of claim 12 wherein 23 said means for coupling is adapted to apply said signals to said drive subsystem to initiate a needle cycle in response to frame translation exceeding a 24 25 threshold magnitude. 26 II27 28

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16. The apparatus of claim 12 wherein said drive subsystem (Original) 1 2 includes speed control circuitry; and wherein said means for coupling is adapted to apply said signals to said speed 3 4 control circuitry. 5 6 // 7 // 8 9 // // 10 // 11 12 // // 13 // 14 15 // // 16 // 17 // 18 // 19 // 20 21 // 22 // // 23 // 24 25 II// 26 // 27 28

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